

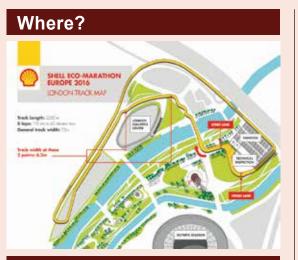


# **SHELL ECO MARATHON EUROPE 2016**

Texas A&M University at Qatar Mechanical Engineering – Class of 2016

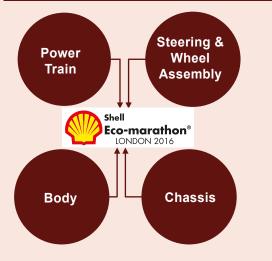
## **Background and Overview**

Shell Eco Marathon (SEM) is a world-wide competition that challenges students to design, build and test ultra-energy-efficient vehicles. Texas A&M at Qatar will be participating under Urban Concept Group in SEM Europe 2016 which will be taking place in London, UK from June 30 to July 3rd, 2016. The race track will be around the iconic of the Queen Elizabeth Olympic Park. The vehicle will be designed adapting this track relative to steering, braking, stability and safety. The team aims to complete 8 laps in less than 43 minutes to qualify for nominating TAMUQ's name to the lead at the competition.



## Sub-Systems

Car Assembly



## About the Competition

## URBAN CONCEPT

TAMUQ is participating under the category of UC i.e. designing an energy efficient vehicle that is closer in appearance to today's production type passenger cars

## What is operating the vehicle?

The team will be designing a battery electric vehicle

## **Requirement for Valid Attempt**

Each team must complete 8 laps in a maximum time of 43 minutes with an average speed of approximately 25 km/h covering a total distance of 17.92 km between start and finish lines.

# **Highlights on Rules and Regulations**

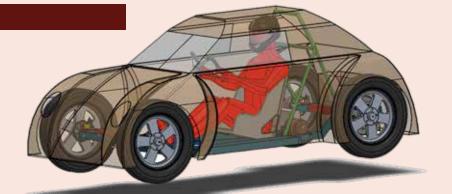
### Vehicle Regulations

- Vehicle height must be between 100 cm and 130 cm
- Body width must be between 120 cm and 130 cm
- Vehicle length must be between 220 cm and 350 cm
- Wheelbase at least 120 cm
- UC vehicle must have exactly 4 wheels
- Chassis must be equipped with roll bar that extends 5 cm around the driver's helmet for full visibility

### **Driver Regulations**

- Full compliance with safe driving and sporting rules
- Minimum driver weight = 70 KG wearing helmet and fire retardant clothing





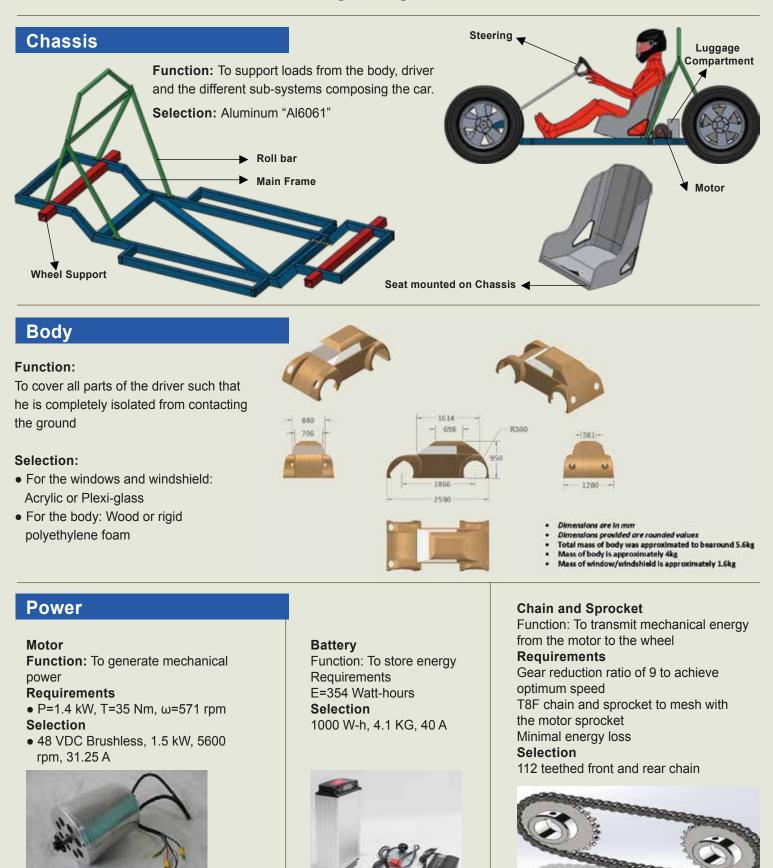




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# Steering, Wheel Assembly and Brakes

### **Steering and Wheel Assembly**

### Functions

- To transmit power to the ground
- To control the direction of vehicle motion
- To interface with the chassis, brakes and power train sub-systems

#### Highlights

- Simple and low weight Go-Kart steering system
- Ackerman geometry to reduce frictional losses while turning
- Michelin tires to fit 16x3.5 wheels

Front View of the Steering System

### **Braking System**

#### **Functions**

- To slow down or stopping the vehicle when it is in motion
- To keep the vehicle stationary when it is parked

### **Highlights**

- Tektro HD T525 mountain bike braking system
- Mineral oil hydraulic braking system
- High performance metal-ceramic brake pads
- Lock device mechanism

### Requirements

- Single braking pedal of surface area 25 cm2
- Two independent braking systems operating in X form
- Brake disk and caliper for each wheel



Brake caliper and rotors (disk) interface with the wheel assembly



Handle interfaces with the chassis and changed into a foot brake-pedal

# **Wheel Assembly**



Back Wheel





Front Wheel

Wheel Used